

OPTICAL SUBASSEMBLY FOR OPTOELECTRONIC DEVICES

Cross-Reference to Related Applications

This application claims the benefit of U.S. Provisional Application Number 60/449,570, filed 21 February 2003.

FIELD OF THE INVENTION

This invention relates to optoelectronic packaging and, more particularly, to the stable alignment of optical components.

Background of the Invention

Optoelectronics is a rapidly expanding technology that plays an increasingly important role in many aspects of modern society (e.g., communication over optical fibers, computer storage and displays, etc.). With the increasing number of actual and potential commercial applications for optoelectronic systems, there is a need to develop cost effective and precise

1 manufacturing techniques for assembling optoelectronic modules
2 (e.g., fiber-optic cable repeaters, transmitters, etc.).
3

4 One of the problems associated with developing such cost
5 effective manufacturing techniques is the high precision
6 required to align components (e.g., lasers, photodiodes,
7 optical fibers, etc.) to assure proper optical coupling and
8 durability. Typically, an optoelectronic module includes a
9 package or housing containing an optoelectronic device (e.g.,
10 semiconductor laser, light emitting diode, photodiode, etc.)
11 coupled to an optical fiber (e.g., single mode, multimode or
12 polarization maintaining) that extends from the package. A
13 major challenge in assembling such optoelectronic modules is in
14 maintaining optimal alignment of the optoelectronic device with
15 the optical fiber to maximize the optical coupling. In order
16 to obtain maximum optical coupling, it is typically desired
17 that the core-center of the optical fiber be precisely aligned
18 with that of the optoelectronic device. In some cases, such as
19 with a single-mode optical fiber, the alignment between the
20 optoelectronic device (i.e., laser) and optical fiber must be
21 within tolerances of 1 μm or less.
22

23 A conventional method for aligning an optoelectronic laser
24 with an optical fiber is known as "active alignment," where the
25 laser is bonded to a substrate and one end of a desired type of

1 optical fiber is positioned in close proximity to a light-
2 emitting surface of the laser in order to transmit light
3 emitted from the laser through the optical fiber. A
4 photodetector, such as a large area photodetector, is
5 positioned at the opposing end of the fiber to collect and
6 detect the amount of light (optical radiation) coupled to and
7 transmitted through the fiber. The position of the fiber is
8 incrementally adjusted relative to the laser either manually or
9 using a machine until the light transmitted through the fiber
10 reaches a maximum, at which time, the optical fiber is
11 permanently bonded to the same substrate that the laser was
12 previously bonded to.

13
14 An optoelectronic photodiode, such as a PIN or APD
15 photodiode, may similarly be coupled to an optical fiber
16 through "active alignment" by bonding the photodiode to a
17 substrate and positioning the end of the optical fiber that is
18 to be coupled to the photodiode in proximity to the light
19 receiving surface of the photodiode. Light is then radiated
20 through the opposing end of the optical fiber using a light
21 source and the position of the fiber is incrementally adjusted
22 relative the photodiode until the photodiode's electrical
23 response reaches a maximum, wherein the optical fiber is then
24 bonded to the substrate supporting the photodiode.

1 Alternatively, such "active alignment" of an
2 optoelectronic device (e.g., laser or photodiode) to an optical
3 fiber has been attempted by initially bonding the optical fiber
4 to the substrate, moving the optoelectronic device into
5 alignment by detecting the maximum optical radiation through
6 the fiber, and then bonding the aligned optoelectronic device
7 to the substrate supporting the fiber. It is highly desirable,
8 however, to be able to accurately align an optical device with
9 an optical fiber using a method that is quick and inexpensive.

10

11 It would be highly advantageous, therefore, to remedy the
12 foregoing and other deficiencies inherent in the prior art.

13

14 It is an object of the present invention to provide a new
15 and improved subassembly for optoelectronic modules.

16

17 Another object of the present invention is to provide a
18 new and improved subassembly for optoelectronic modules that
19 can be easily incorporated into any of the present optoelectronic
20 modules.

21

22 Another object of the present invention is to provide a
23 new and improved subassembly for optoelectronic modules that
24 provides greater flexibility in optical alignment of
25 optoelectronic components.

Summary of the Invention

Briefly, to achieve the desired objects of the instant invention in accordance with a preferred embodiment thereof, an optoelectronic subassembly for optoelectronic modules is provided that includes a supporting substrate having a mounting surface and an opposed surface with an optoelectronic device mounted on the mounting surface. At least three offset arms are provided each including a substrate-mounting portion, a supporting-structure-mounting portion, and a linking portion. The substrate-mounting portion and the supporting-structure-mounting portion include substantially parallel surfaces with the linking portion extending at an angle therebetween and at least the linking portion includes deformable material for allowing small changes in the angle. One of the parallel surfaces of each of the at least three offset arms is mounted on one of the mounting surface of the supporting substrate and the opposed surface.

In a specific embodiment, a supporting structure with a trench formed therein is provided with an optical lens assembly positioned thereon. The optical lens assembly can be, for example, an optical fiber, a lens, combinations thereof, or similar devices or structures which are desired to interact with light received from or supplied to the optoelectronic device. One of the parallel surfaces of each of the at least

1 three offset arms is mounted on one of the mounting surface of
2 the supporting substrate and the opposed surface and the other
3 of the parallel surfaces of each of the at least three offset
4 arms is mounted on the mounting surface of the support
5 structure with the supporting substrate suspended in the
6 trench. The linking portions of the at least three offset arms
7 are then deformed to move the optoelectronic device into
8 optical alignment with the optical lens assembly.

9
10 The desired objects of the instant invention are further
11 realized in another method of mounting and aligning an
12 optoelectronic subassembly for optoelectronic modules on a
13 supporting structure. This method includes the step of
14 providing a supporting substrate having a mounting surface and
15 an opposed surface and an optoelectronic device mounted on the
16 mounting surface. A supporting structure having a mounting
17 surface and an optical lens assembly mounted on the mounting
18 surface is also provided. The method further includes placing
19 a layer of adhesive in a semi-liquid state on the mounting
20 surface proximate the optical lens assembly, placing the
21 opposite surface of the supporting substrate on the layer of
22 adhesive, and applying a force to the supporting substrate to
23 optically align the optoelectronic device with the optical lens
24 assembly. Once alignment is achieved the adhesive is allowed
25 to cure with the optoelectronic device and the optical lens
26 assembly optically aligned.

1 Brief Description of the Drawings

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3 The foregoing and further and more specific objects and
4 advantages of the instant invention will become readily
5 apparent to those skilled in the art from the following
6 detailed description of a preferred embodiment thereof taken in
7 conjunction with the drawings, in which:

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9 FIG. 1 is a perspective view of an optoelectronic
10 subassembly in accordance with the present invention;

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12 FIG. 2 is a front view of the optoelectronic subassembly
13 illustrated in FIG. 1.

14

15 FIG. 3 is a front view of the optoelectronic subassembly
16 illustrated in FIGS. 1 and 2 positioned on a supporting
17 structure; and

18

19 FIG. 4 is a plan view of another embodiment of an optical
20 subassembly in accordance with the present invention.

Detailed Description of the Drawings

Turning now to FIG. 1, an optoelectronic subassembly 5 in accordance with the present invention is illustrated. Optoelectronic subassembly 5 includes a device mount or supporting substrate 10, having an upper or mounting surface 19 onto which an optical device 12 is mounted. At the present time, substrate 10 and optical device 12 are usually purchased as a component from a manufacturer. In this embodiment, substrate 10 includes a ceramic material layer. However, it will be understood that substrate 10 can include other suitable materials, such as a semiconductor, an insulator, a conductor, or the like. Further, substrate 10 is illustrated as including a single ceramic material layer for simplicity. It will be understood, however, that substrate 10 can include more than one layer. Further, it will be understood that mount or substrate 10 can include other electronic or optoelectronic devices or circuitry.

In this embodiment, for purposes of explanation, optical device 12 includes a semiconductor laser which emits light, represented by arrow 17. However, optical device 12 can include other light emitting or receiving optoelectronic devices, such as a light emitting diode, a photodiode, or the like. It will of course be understood that arrow 17 will be directed in the opposite direction when device 12 is a light

1 sensing device. Also, laser 12 is illustrated as being
2 positioned on substrate 10 for illustrative purposes only and
3 laser 12 or substrate 10 can include a heatsink or similar heat
4 conducting structure.

5
6 In the preferred embodiment, optoelectronic subassembly 5
7 includes offset arms 14, 16, 18, and 20 which are fixedly
8 attached to substrate 10. Offset arms 14, 16, 18, and 20 are
9 fixedly attached to substrate 10 using an adhesive, a solder,
10 or a similar material which provides suitable properties for
11 adhesion over a desired temperature range. Further, it will be
12 understood that offset arms 14, 16, 18, and 20 can include a
13 conductive material, such as a metal or a similar material,
14 which provides mechanical strength to support substrate 10 and
15 optical device 12. In this preferred embodiment, at least some
16 of offset arms 14, 16, 18, and 20 are electrically coupled
17 (e.g. by direct connection, wire bonding, etc.) to optical
18 device 12 and any other electronics (e.g. monitoring diodes,
19 amplifiers, etc.) mounted on substrate 10. Also in this
20 embodiment, offset arms 14, 16, 18, and 20 are fabricated from
21 a material which can be relatively easily bent or formed into a
22 desired shape, as will be discussed presently, and which will
23 hold the desired shape against normal forces (e.g. dropping,
24 jarring, etc.) once it is achieved.

1 In this embodiment, four offset arms (i.e. arms 14, 16,
2 18, and 20) are illustrated for simplicity and ease of
3 discussion. However, it will be understood that any number of
4 arms greater than two can be used to mount substrate 10 and
5 optical device 12 and the use of four arms in this embodiment
6 is not intended to limit the scope of the invention.

7
8 Referring additionally to FIG. 2, a front view
9 perpendicular to a line A-A' of optoelectronic subassembly 5 is
10 illustrated. As can be seen clearly in FIGS. 1 and 2, in this
11 embodiment, offset arms 14, 16, 18, and 20 are each formed with
12 a similar or standard offset. That is (using arm 14 as an
13 example), arm 14 includes a substrate-mounting portion 14a and
14 a substantially parallel but offset supporting-structure-
15 mounting portion 14b. A linking portion 14c is formed to angle
16 between offset portions 14a and 14b and is at least partially
17 deformable, i.e. the angle of linking portion 14c can be
18 changed to change the offset between portions 14a and 14b.

19
20 Referring specifically to FIG. 2, it is shown that arms 14
21 and 16 (and arms 18 and 20) are formed so that angled portions
22 14c and 16c are at an angle θ , relative to mounting surface 19
23 of substrate 10 (and to portions 14a and 14b and to portions
24 16a and 16c, respectively). Further, a lower surface of
25 portions 14b and 16b of arms 14 and 16, respectively, are a

1 vertical distance 11 from surface 19. However, because at
2 least the linking portion of the offset arms is deformable,
3 distance 11 and, consequently, angle θ , can be adjusted by
4 deforming or bending arms 14 and 16. The distance 11 and the
5 angle θ between the lower surface of portions 14b and 16b of
6 arms 14 and 16, respectively, (and arms 18 and 20) and surface
7 19 are assumed to be substantially equal (i.e. within a
8 manufacturing tolerance for arms 14, 16, 18, and 20) for
9 illustrative purposes only and ease of discussion.

10
11 Turn now to FIG. 3 which illustrates a front view
12 perpendicular to line A-A' of optoelectronic subassembly 5
13 wherein subassembly 5 is positioned or suspended within a
14 trench 23 in a supporting structure 15. Subassembly 5 is
15 positioned such that the lower surface of portions 14b and 16b
16 of arms 14 and 16 (and similarly for arms 18 and 20) engage an
17 upper or mounting surface of support structure 15. Arms 14,
18 16, 18, and 20 can be fixedly attached to support structure 15
19 using an adhesive, a solder, or a similar material with a
20 desired property of adhesion. Also, in a preferred embodiment,
21 the lower surface of some or all of offset arms 14, 16, 18, and
22 20 are electrically connected to I/O pads 25 on the surface of
23 supporting structure 15.

1 In this explanation, arms 14, 16, 18, and 20 are
2 illustrated as being mounted so that the linking portions angle
3 upwardly at an angle θ , however it will be understood that the
4 arms could be reversed so that the linking portions angle
5 downwardly from surface 19 at the angle θ in applications where
6 this arrangement would bring device 12 into closer optical
7 alignment with other devices (not shown) mounted on support
8 structure 15. Also, in other applications (e.g. where optical
9 lenses, fibers, etc. are mounted in or in alignment with trench
10 23) substrate 10 and device 12 could be reversed or rotated 180
11 degrees and arms 14, 16, 18, and 20 could be attached to the
12 surface opposite surface 19 in either of the above described
13 orientations.

14
15 The deforming or bending of arms 14 and 16 allows optical
16 device 12 to be adjusted (generally vertically) relative to an
17 optical lens assembly (not shown) wherein it is desired to
18 optically couple light 17 into (or out of) the optical lens
19 assembly. It will be understood that the optical lens assembly
20 can be, for example, an optical fiber, a lens, combinations
21 thereof, or similar devices or structures which are desired to
22 interact with light 17. It will be understood that adjustment
23 of device 12 (especially in a vertical direction) can generally
24 be accomplished with the application of sufficient pressure

1 (upwardly or downwardly) on substrate 10 to deform the angled
2 portions of the arms.

3

4 Turning now to FIG. 4, another embodiment of an
5 optoelectronic subassembly 7', in accordance with the present
6 invention, is illustrated. Components of this embodiment that
7 are similar to components of the embodiment of FIG. 3, are
8 designated with similar numbers and a prime is added to
9 indicate the different embodiment. Subassembly 7' includes
10 substrate 10' with optical device 12' positioned thereon.
11 Substrate 10' is fixedly attached to support structure 15'
12 (generally within a trench or adjacent a step or the like)
13 using an adhesive 26' with a thickness 21'. It will be
14 understood that adhesive 26' can include an epoxy, a eutectic,
15 a glue layer or a similar material with a desired property for
16 adhesion and an initial liquid or semi-liquid state
17 (sufficiently solid or adhesive to maintain thickness 21' with
18 no outside force other than gravity).

19

20 In this embodiment, subassembly 7' is initially fabricated
21 using a D/A tip 20' with arms 22' and 24'. It will be
22 understood that arms 22' and 24' are designed to frictionally
23 engage an upper surface of support structure 15' and control a
24 pressure applied to substrate 10' from D/A tip 20'. D/A tip
25 20' and arms 22' and 24' can be from an attach tool wherein D/A
26 tip 20' could be, for example, threadedly engaged within arms

1 22' and 24', and is used to adjust the pressure applied by tip
2 20' to substrate 10' when adhesive 26' is in a liquid or semi-
3 liquid state. Through the threaded feature (if included) of
4 D/A tip 20', substrate 10' can be moved vertically very minute
5 amounts until a desired optical alignment is achieved, after
6 which adhesive 26' is allowed to set. The pressure applied to
7 substrate 10' will change thickness 21' so that optical device
8 12' is aligned (generally vertically) with an optical lens
9 assembly 28'. It will be understood that optical lens assembly
10 28' can be, for example, an optical fiber, a lens, or a similar
11 device or structure which is desired to interact with light
12 17'.

13
14 Thus, a new and improved subassembly for optoelectronic
15 modules has been disclosed. The new and improved subassembly
16 can be easily incorporated into any of the present optoelectric
17 modules and greatly improves flexibility in optical alignment
18 of optoelectronic components. Further, any of the embodiments
19 disclosed are relatively simple and inexpensive to incorporate
20 into any of the present day structures or into new structures.

21
22 Various changes and modifications to the embodiments
23 herein chosen for purposes of illustration will readily occur
24 to those skilled in the art. To the extent that such
25 modifications and variations do not depart from the spirit of
26 the invention, they are intended to be included within the

1 scope thereof which is assessed only by a fair interpretation
2 of the following claims.

3.

4 Having fully described the invention in such clear and
5 concise terms as to enable those skilled in the art to
6 understand and practice the same, the invention claimed is: